ΠJ

U

Fig. 1A.

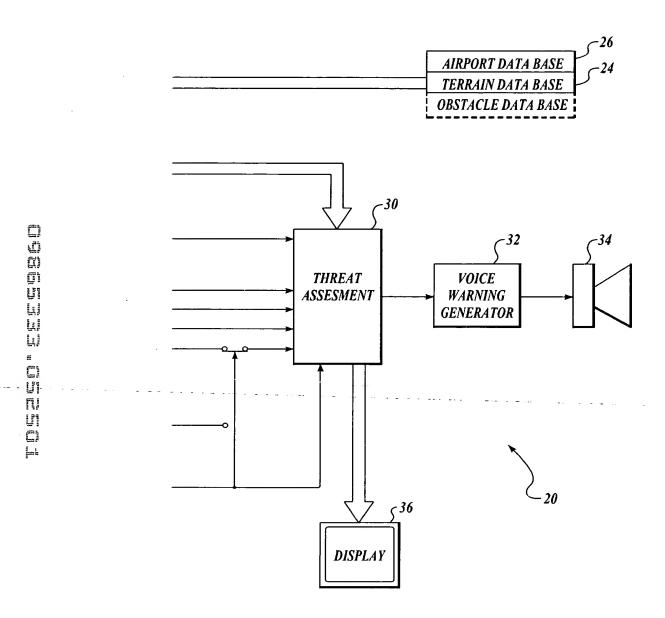
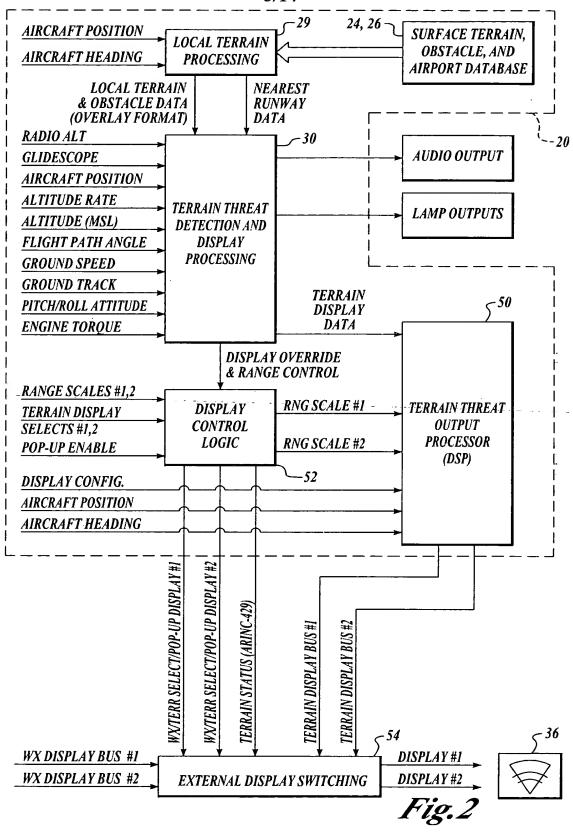


Fig.1B.



## MODE I EXCESSIVE DESCENT RATE "SINKRATE" "PULL UP!"

MODE 2

EXCESSIVE TERRAIN

CLOSURE RATE

"TERRAIN... TERRAIN"

"PULL UP!"

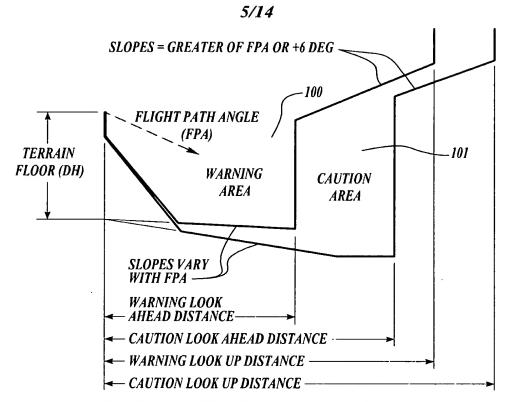
MODE 6
AUTOROTATION
ALTITUDE CALL-OUTS
"...ONE HUNDRED..."
BANK ANGLE
"BANK ANGLE"
TAIL STRIKE
"TAIL TOO LOW"

MODE 3
SINK AFTER TAKEOFF
"DON'T SINK"

MODE 5

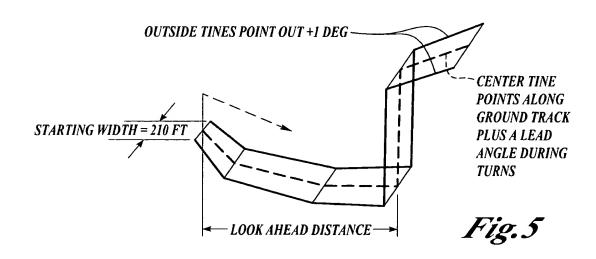
EXCESSIVE DEVIATION
BELOW GLIDESLOPE
"GLIDESLOPE"

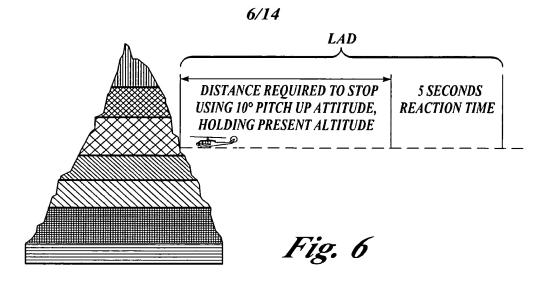
MODE 4
TOO CLOSE TO TERRAIN
"TOO LOW - TERRAIN"
"TOO LOW -GEAR"

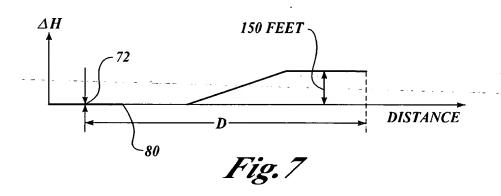


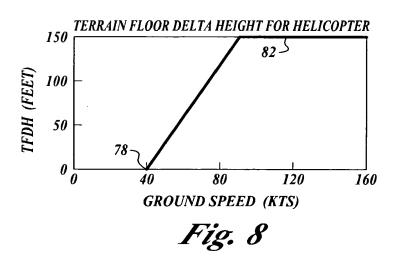
LOOK AHEAD DISTANCES VARY WITH GROUND SPEED AND DISTANCE TO RUNWAY TERRAIN FLOOR VARIES WITH DISTANCE TO RUNWAY

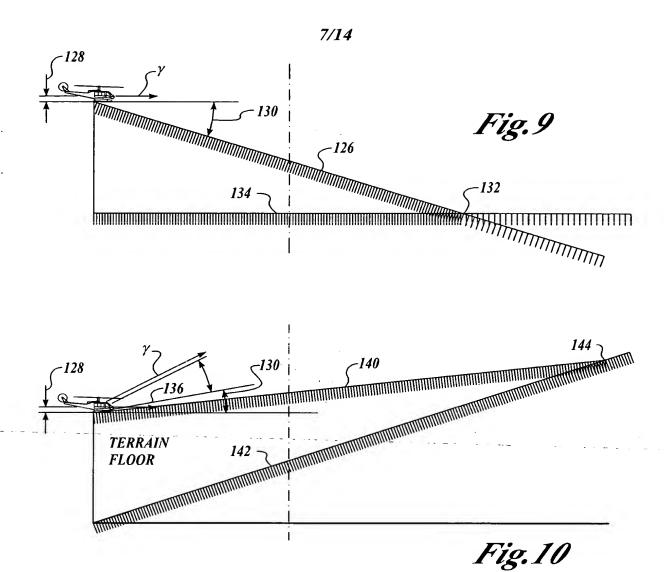
## Fig.4

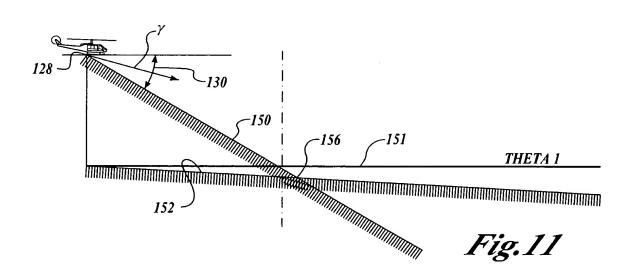












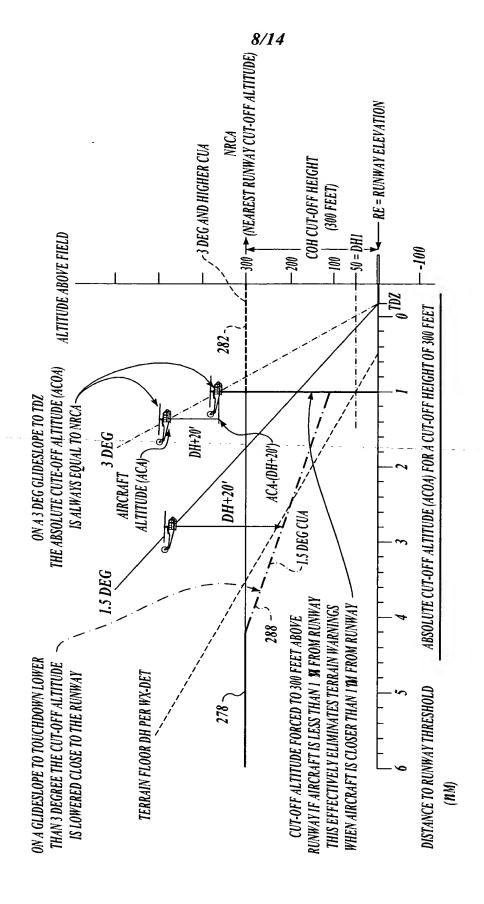
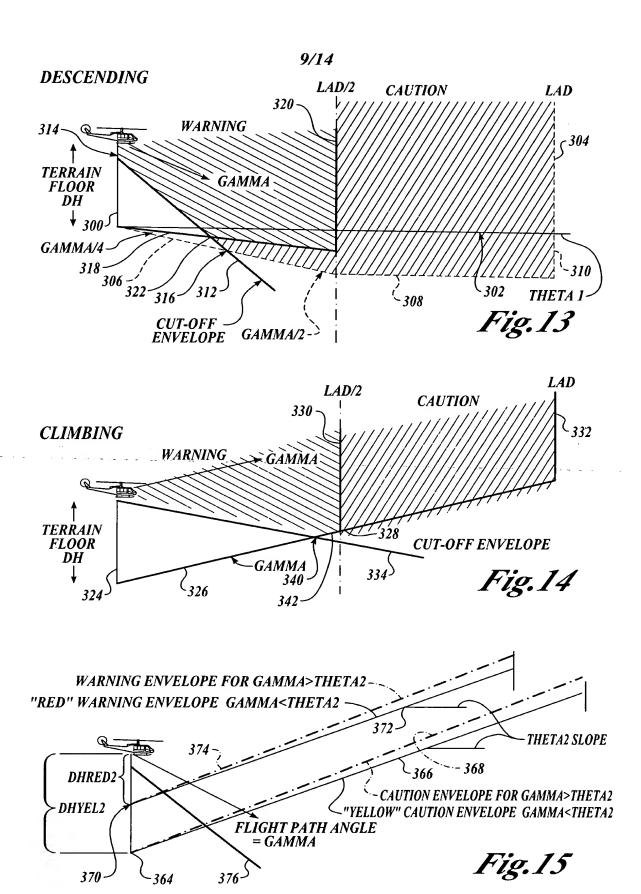
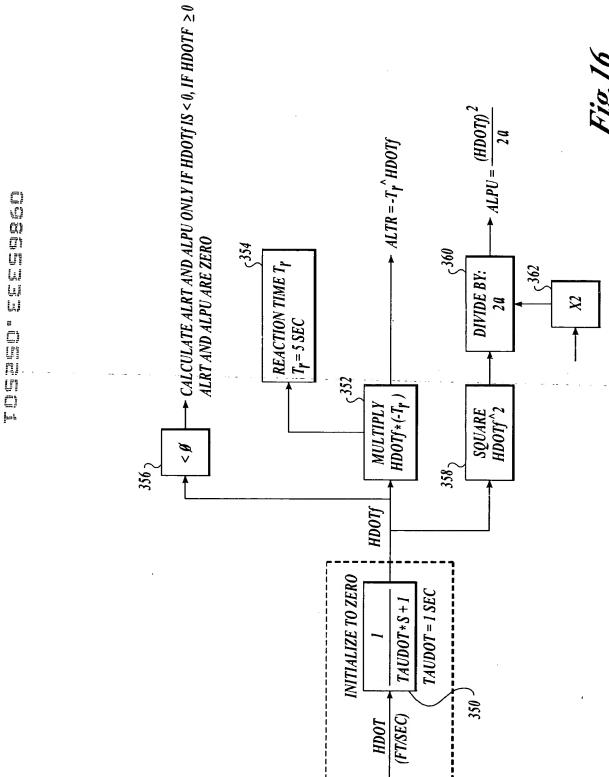
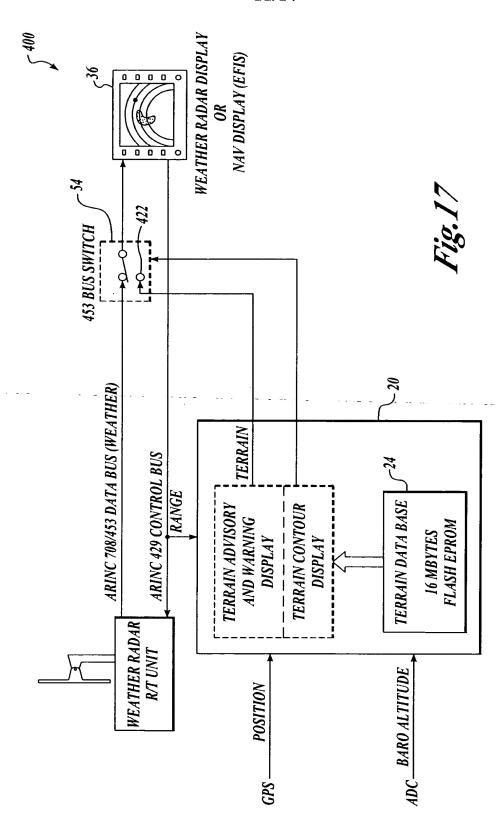
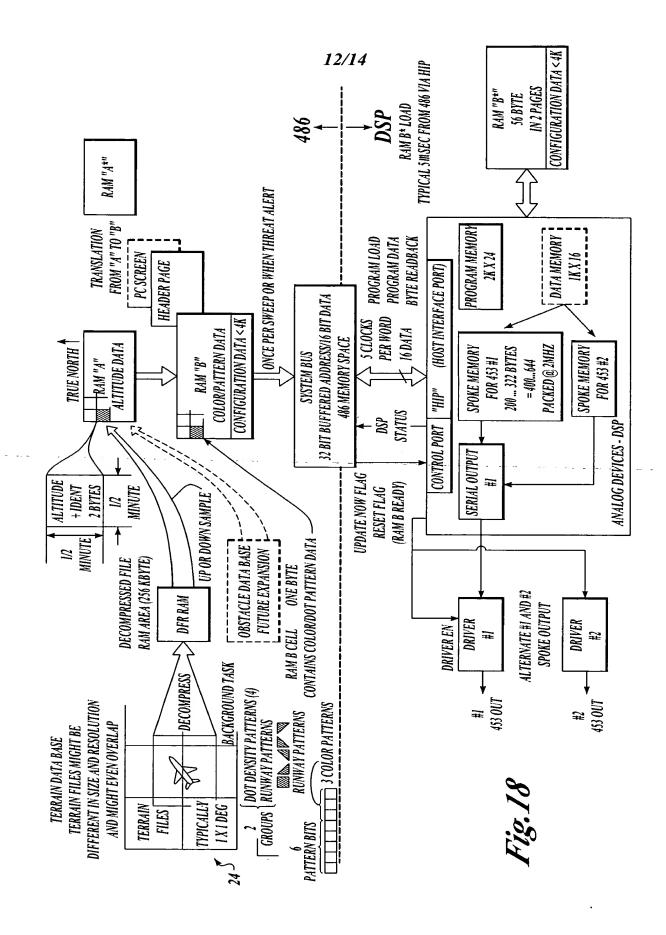


Fig. 12









13/14

## BACKGROUND TERRAIN DISPLAY - NORMAL APPROACH

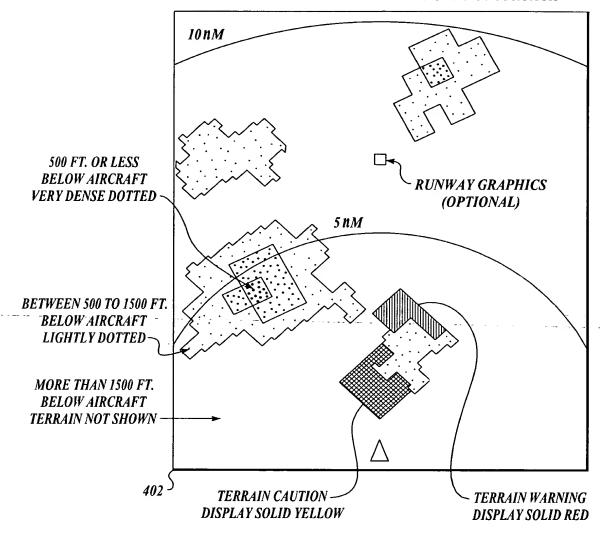


Fig.19



